

YANYU ZHANG

yzhan831@ucr.edu || [LinkedIn](#) || [Google Scholar](#) || [GitHub](#) || [Personal Website](#)
(617) 935-7005 || 5555 W Ina Rd, Apt 7206, Tucson, AZ, 85743

EDUCATION

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| University of California, Riverside Ph.D. in Electrical Engineering, Advisor: Wei Ren | Sep. 2021 - Mar. 2025 |
| Boston University M.S. in Electrical and Computer Engineering, Advisor: John Baillicul | Sep. 2019 - May 2021 |
| University of Detroit Mercy B.S. in Robotics | Sep. 2018 - May 2019 |
| Beijing University of Chemistry Technology B.S. in Robotics | Sep. 2015 - Jun. 2018 |

RESEARCH EXPERIENCE

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| University of California, Riverside <i>Research Assistant, Cooperative Vehicle Networks Laboratory (COVEN)</i> | Sep. 2021 - Mar. 2025 <i>Riverside, CA</i> |
| <ul style="list-style-type: none">• Cooperative visual-inertial odometry with points and lines• NeRF-aided visual-inertial odometry• Infrastructure-less cooperative SLAM for multi-user AR• Extrinsic calibration between camera and LiDAR | |
| Boston University <i>Research Assistant, Boston University Robotics Laboratory</i> | Jan. 2020 - May 2021 <i>Boston, MA</i> |
| <ul style="list-style-type: none">• Motion planning, Optical flow, SLAM | |

INDUSTRY EXPERIENCE

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| VisionNav Robotics USA Inc. <i>Staff Algorithm Engineer, SLAM</i> | Apr. 2025 - Present <i>Remotely</i> |
| <ul style="list-style-type: none">• 3DGS-Aided SLAM, LiDAR-Inertial-Visual Odometry, SLAM | |
| VisionNav Robotics USA Inc. <i>Algorithm Engineer Intern, SLAM</i> | Dec. 2024 - Mar. 2025 <i>Remotely</i> |
| <ul style="list-style-type: none">• LiDAR-Inertial Odometry, SLAM | |
| Mitsubishi Electric Research Laboratories (MERL) <i>Research Intern</i> | Jan. 2023 - Apr. 2023 <i>Cambridge, MA</i> |
| <ul style="list-style-type: none">• Sensor Fusion, State Estimation, SLAM | |

ACADEMIC SCHOLARSHIPS AND AWARDS

- **Fellowship:** 2021-2022 UCR Dean's Distinguished Fellowship Award
- **Travel Award:** 2024 ACC Student Travel Award
- **Travel Award:** 2023 CCTA Student Travel Award

TEACHING EXPERIENCE

University of California, Riverside

Teaching Assistant

Sep. 2022 - Dec. 2024

Riverside, CA

- Fall 2024: EE005 Circuits and Electronics (Undergraduate Course)
- Summer 2024: EE005 Circuits and Electronics (Undergraduate Course)
- Spring 2024: EE132 Automatic Control (Graduate Course)
- Fall 2023: EE230 Mathematical Methods for Electrical Engineers (Graduate Course)
- Summer 2023: EE005 Circuits and Electronics (Undergraduate Course)
- Spring 2023: EE132 Automatic Control (Graduate Course)
- Fall 2022: EE230 Mathematical Methods for Electrical Engineers (Graduate Course)

Boston University

Teaching Assistant

Jan. 2021 - May 2021

Boston, MA

- Spring 2021: EC500 Building Software (Graduate Course)

PUBLICATIONS

- [11] J. Xu, D. Wang, **Y. Zhang** and W. Ren, "Multi-robot Dual Reinforcement Learning Framework for Hybrid Motion Planning" in *Proceedings of the American Control Conference (ACC)*, New Orleans, LA, USA, May 26 - May 29, 2026. (Under Review)
- [10] **Y. Zhang**, J. Xu and W. Ren, "PLK-Calib: Single-shot and Target-less LiDAR-Camera Extrinsic Calibration using Plucker Lines" in *IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)*, Hangzhou, China, Oct. 19 - Oct. 25, 2025.
- [9] **Y. Zhang**, D. Wang, J. Xu, M. Liu, P. Zhu and W. Ren, "NeRF-VIO: Map-based Visual-Inertial Odometry with Initialization Leveraging Neural Radiance Fields" in *IEEE International Conference on Automation Science and Engineering (CASE)*, Los Angeles, CA, USA, Aug. 17 - Aug. 21, 2025.
- [8] **Y. Zhang**, "Towards AI-Aided Multi-User AR: Cooperative Visual-Inertial Odometry Enhanced by Point-Line Features and Neural Radiance Fields" in Doctoral dissertation, University of California, Riverside, 2025.
- [7] **Y. Zhang**, M. Greiff, W. Ren and K. Berntorp, "Distributed Road-Map Monitoring Using Onboard Sensors" in *Proceedings of the American Control Conference (ACC)*, Toronto, Canada, Jul. 8 - Jul. 12, 2024.
- [6] J. Xu, P. Zhu, **Y. Zhang** and W. Ren, "Cooperative 3-D Target State Estimation and Active Tracking" in *Proceedings of the IEEE Conference on Decision and Control (CDC)*, Marina Bay Sands, Singapore, Dec. 13 - Dec. 15, 2023.
- [5] **Y. Zhang**, P. Zhu and W. Ren, "PL-CVIO: Point-Line Cooperative Visual-Inertial Odometry" in *Proceedings of the IEEE Conference on Control Technology and Applications (CCTA)*, Bridgetown, Barbados, Aug. 16 - Aug. 18, 2023.
- [4] C. Boretti, P. Bich, **Y. Zhang** and J. Baillieul, "Visual Navigation Using Sparse Optical Flow and Time-to-Transit" in *Proceedings of the IEEE International Conference on Robotics and Automation (ICRA)*, Philadelphia, PA, USA, May 23 - May 27, 2022.
- [3] **Y. Zhang**, J. Song and S. Li, "3D Object Detection and Tracking Using Monocular Camera in CARLA" in *Proceedings of the IEEE International Conference on Electro Information Technology (EIT)*, Mt. Pleasant, MI, USA, May 14 - May 15, 2021.
- [2] **Y. Zhang** and O. Alshaykh, "5G Utility Pole Planner Using Google Street View and Mask R-CNN" in *Proceedings of the IEEE International Conference on Electro Information Technology (EIT)*, Chicago, IL, USA, Jul. 31 - Aug. 1, 2020.

- [1] **Y. Zhang**, X. Wang, X. Wu, W. Zhang, M. Jiang and M. Al-Khassaweneh, "Intelligent Hotel ROS-based Service Robot" in *Proceedings of the IEEE International Conference on Electro Information Technology (EIT)*, Brookings, SD, USA, May 20 - May 22, 2019.

PATENTS

- [1] **Y. Zhang**, R. Duan, Z. Zhao, H. Jing, *Intelligent Tennis Ball Picking Robot and Control System*, China patent ZL201820308664.8.

PROFESSIONAL ACTIVITIES

Membership

- IEEE Membership
- IEEE Robotics and Automation Society Membership
- IEEE Control Systems Society Membership

Paper Reviewer

- IEEE Robotics and Automation Letters (RA-L)
- IEEE International Conference on Robotics and Automation (ICRA)
- IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)
- IEEE International Conference on Automation Science and Engineering (CASE)
- IEEE Transactions on Control Systems Technology (TCST)
- American Control Conference (ACC)
- IEEE Conference on Decision and Control (CDC)
- IEEE Conference on Control Technology and Applications (CCTA)